





# Noise mapping: Uncertainty in Calculation Models

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### Content

- Introduction
- What is noise prediction
- What is a model
- Error propagation
- Good practice guide
- Uncertainty caused by unclear methods
- Quality assurance
- Summery and conclusion



## **Noise predictions**

#### Why?

- Quantification
- Effect or impact on the environment
- Check on laws, guidelines or recommendations
- Calculations with measures (source and propagation)

#### Where?

- House/dwellings
- Other noise sensitive buildings/areas like: hospitals, etc.
- Offices, hotels and other places where people live, stay or work
- Nature areas, recreation areas, cemeteries, etc.

#### What?

- Annoyance due to noise. (Equivalent noise level at the facades)
- The  $L_{eq}$  representative for a specific facade for a long period (years)
- The L<sub>eq</sub> must be reproducible.



### What is a Noise Prediction Model?

#### Meta Model, Framework or Method

- A set of ideas for organizing a process about a particular situation:
  - ✓ General
  - ✓ Higher level
  - ✓ Conceptual
  - ✓ 'A description of'
  - 🗸 Tool

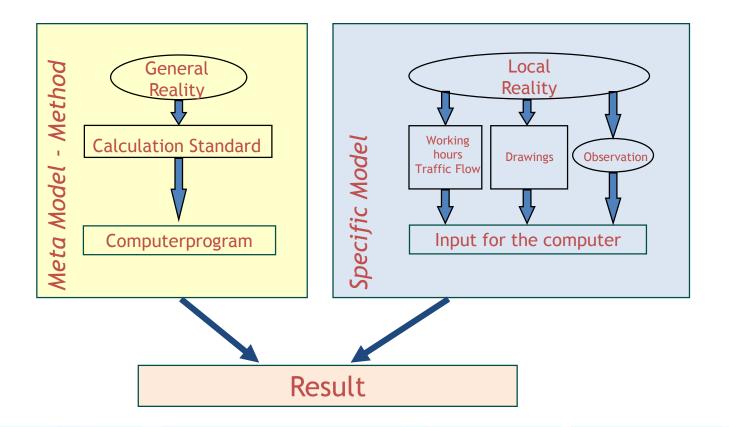
#### Specific Model

- A useful representation of a specific situation
  - ✓ Typical for a situation
  - ✓ Specific applicable
  - ✓ Discrete

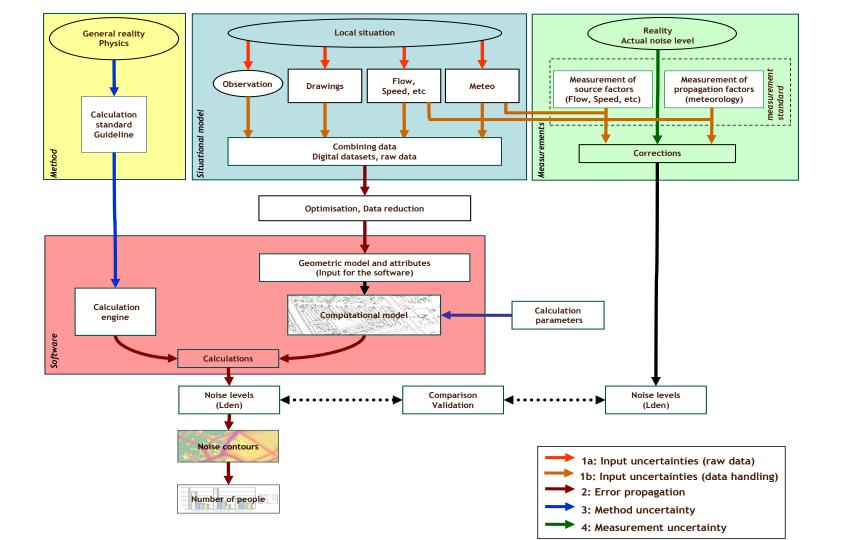




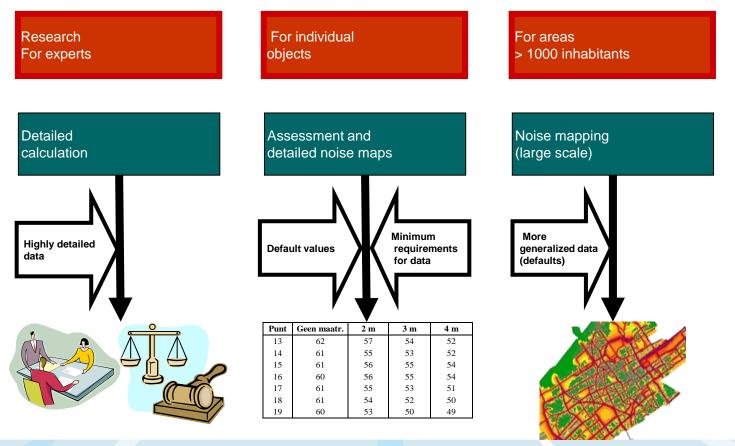
### What is a Model?







## Field of application





### **Representative and reproducible**

For road traffic noise this means that the calculation is based on:

- average traffic flow;
- average noise emission of cars and light and heavy trucks;
- average of the type of tyres (e.g. winter tyres);
- average speed of the traffic;
- average road surface;
- average asphalt temperature (e.g. -0.1 dB/°C).

Defined meteorological situation (weather situation):

- average propagation;
- down wind propagation;
- wind direction;
- air temperature;
- humidity;
- air pressure;
- including/excluding reflections water/snow;
- etc.

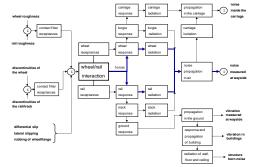


## Generation mechanism of rolling noise

The excitation is the result of 'fine' irregularities on the running surfaces of wheel and rail.

- Roughness:
  - amplitude between approximately 0,2  $\mu$ m and 200  $\mu$ m.
  - wavelengths between approximately 2 mm and 200 mm.
- Long-pitch corrugation:

Visible roughness or roughness in an extreme form.



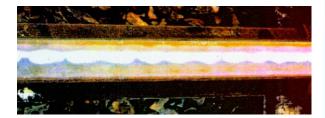
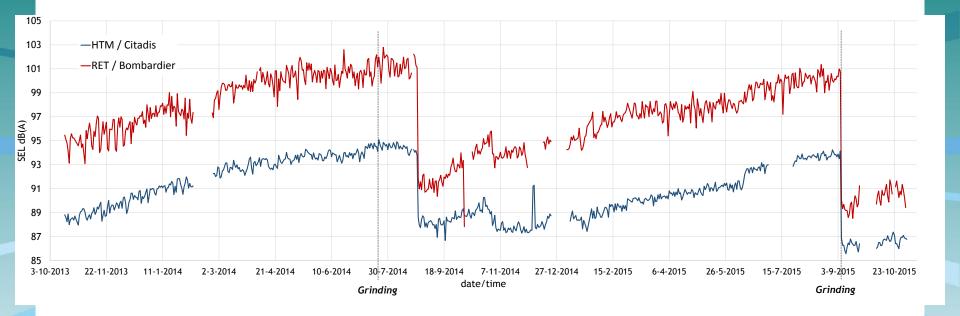


Diagram of the excitation mechanisms for noise and vibration.



### Noise monitoring railway line over more than 2 years



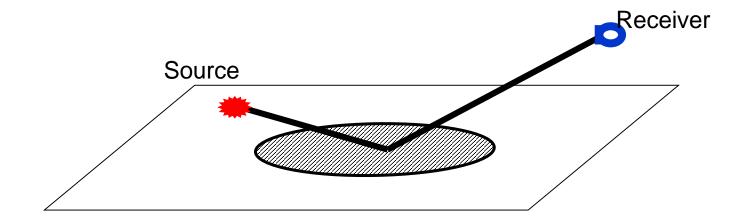


## **Propagation - Reflections**



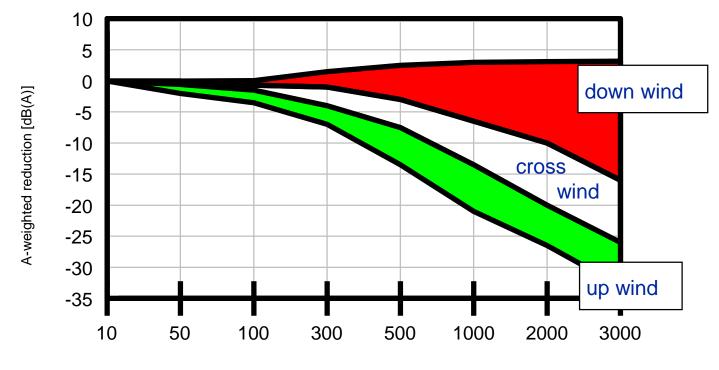


## **Propagation - Fresnel Zone**





## Influence of meteo



distance [m]

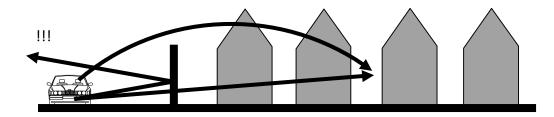




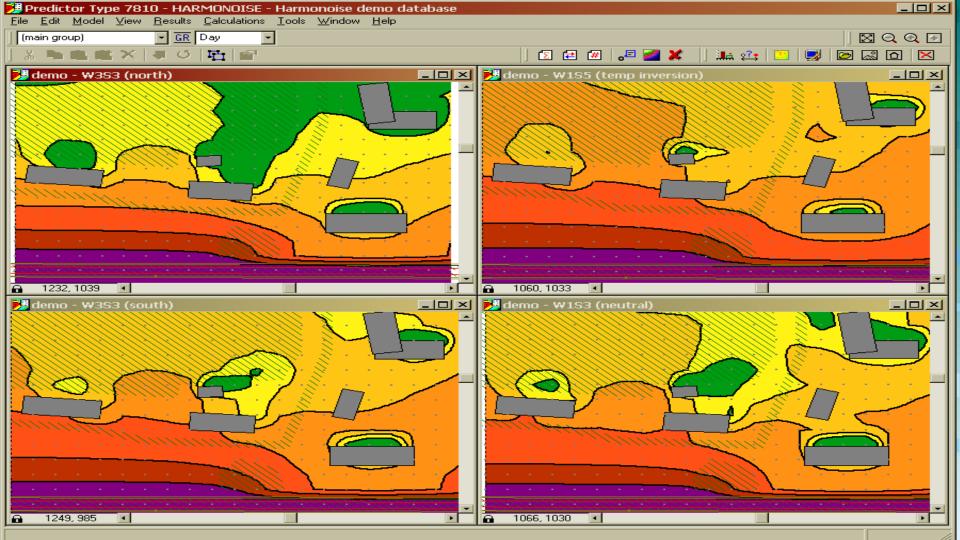
Ray curvature caused by vertical wind speed and air temperature gradients

Sound speed profile influenced by "macro terrain roughness"

Special attention for reflected propagation paths







## Noise mapping process/steps

- 1. (GIS) Data selection Height lines, buildings, ground cover, roads/railways/industry, barriers etc.
- 2. Data validation and economization Missing data, wrong data, out of date, too detailed etc.
- 3. Calculation Optimization settings e.g. error margin, fetching radius
- 4. Results validation Compare with (long term) measurements
- 5. Results analysis Confront with demographic data: number of inhabitants per 5 dB noise class
- 6. Publication noise maps Web site



#### Good practice guide

- The user of the software
  - must know exactly what he/she is calculating
  - $\circ$  should be aware of the limitations of the calculation method
  - o must also be aware of the sensitivities of the standard
- Other guidance for making correct calculations
  - Low flow roads and the lowest flow
  - Calculation distance for busy roads / highways i.r.t. low noise levels
  - Number of reflections....
  - Etcetera, etcetera
- Guidance for input data Garbage in, garbage out



Item	Aspect	Group A	Group B	Group C	Group D	Group E
Ground model	Ground height, contours, TINs etc (Vertical)	<0.5m	>0.5m-<1.2m	>1.2m-<2.5m	>2.5m-<5.0m	>5.0m
	Ground height, contours, TINs etc (Horizontal)	<1.5m	>1.5m-<4.0m	>4.0m-<8.0m	>8.0m-<15m	>15m
	Profile edges (Vertical)	<0.5m	>0.5m-<1.2m	>1.2m-<2.5m	>2.5m-<5.0m	>5.0m
	Profile edges (Horizontal)	<1.5m	>1.5m-<4.0m	>4.0m-<8.0m	>8.0m-<15m	>15m
	Equal height contour spacing (Vertical)	<1.0m	>1.0m-<3.0m	>3.0m-<8.0m	>8.0m-<15m	>15m
Buildings	Vertical	<1.5m	>1.5m-<4.0m	>4.0m-<8.0m	>8.0m-<15m	>15m
	Horizontal	<1.5m	>1.5m-<4.0m	>4.0m-<8.0m	>8.0m-<15m	>15m
	Minimum Size (m <sup>2</sup> )	<5m <sup>2</sup>	$>5m^2-<15m^2$	>15m <sup>2</sup> -<30m <sup>2</sup>	>30m <sup>2</sup> -<50m <sup>2</sup>	>50m <sup>2</sup>
	Absorption coefficient	within 10%	Use absorption classes	Use absorption classes	Reflective by default	Reflective by default
Barriers	Vertical (re road surface)	<0.5m	>0.5m-<1.0m	>1.0m-<2.0m	>2.0m-<5.0m	>5.0m
	Horizontal (re road surface)	<1.5m	>1.5m-<4.0m	>4.0m-<8.0m	>8.0m-<15m	>15m
	Minimum Height (m)	<1.0m	>0.5m-<1.0m	>1.0m-<2.0m	>2.0m-<5.0m	>5.0m
	Minimum Length (m)	<10m	>10m-<25m	>25m-<40m	>40m-<100m	>100m
	Absorption coefficient	within 10%	Use absorption classes	Use absorption classes	Reflective by default	Reflective by default
Ground cover	Ground factor (%)	<5%	>5%-<10%	>10%-<25%	>25%-<50%	>50%
	Surface minimum size (m <sup>2</sup> )	<5m <sup>2</sup>	>5m <sup>2</sup> -<15m <sup>2</sup>	>15m <sup>2</sup> -<30m <sup>2</sup>	>30m <sup>2</sup> -<50m <sup>2</sup>	>50m <sup>2</sup>



#### What is a Noise Prediction Standard?

A prediction standard is:

> described on <u>paper</u> and authorized by law, a standard or a guideline.

> <u>not</u> computer software.

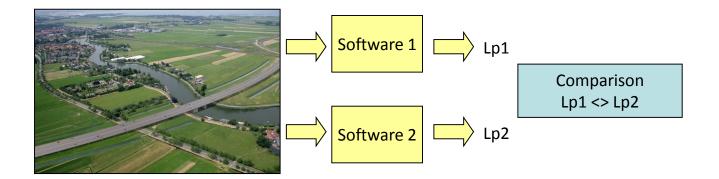
Computer software is always an <u>interpretation</u> of a paper document.

The user must know exactly what he/she is calculating. The user should be aware of the limitations of the calculation method. The user must also be aware of the sensitivities of the standard.



#### Uncertainties in the standards

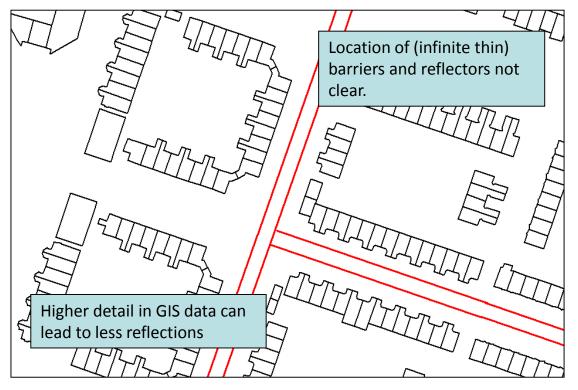
- All prediction standards still contain ambiguous algorithms and unclear text.
- No guidance on converting general purpose GIS data into calculation data formatted in accordance with the standard
- This leads to significant differences between software products based on the same standard.





### Uncertainties in the standards

Example unclear use of GIS data





Uncertainties in the standards Some examples of unclear text

- "In case of parallel objects"
- "2 switches per 100 meter"
- "30% gaps <u>along</u> a road"
- "In case of multiple screens take the screen that has the highest screening effect"
- "Double diffraction will occur in the case of <u>thick</u> barriers and/or <u>well</u> separated objects"



## Validations and quality assurance

- In most cases prediction standards do not include test cases.
- In most cases there is no official certification or validation procedure for noise prediction software.
- In most cases there is no official helpdesk available on the standard.
- In some cases authorities even 'promote' a certain noise calculation <u>software</u> as the 'unofficial' standard. As a result:
  - Black box, lack of transparency and explanation
  - Monopoly, no open market, no development



## Quality assurance for noise calculation software ISO 17534

ISO 17534-1 (general introduction)

- A declaration of conformity for test cases, when available, is normative
- An estimation of uncertainty is informative.
  - This as a result of deviation from the reference configuration. E.g. optimization settings
- A quality assurance interface (QSI) is informative
  - This to exchange data in a standardized format
- ISO 17534-2 (recommendations for test cases and QSI)
  - 15 general test cases for 1 point source and 1 receiver are described
  - For the QSI a reference is made to DIN 45687. For ISO 9613, SCHALL03 and RLS90 only

ISO 17534-3 (recommendations for interpreting ISO 9613.2)

19 detailed test cases for ISO 9613.2



## ISO 17534 - 3 Recommendations for interpreting ISO 9613.2

- In the working group of ISO no general consensus regarding ISO 17534-3.
  As a result some countries (UK, NL DK,...) voted 'no' to the final proposal.
  However the standard was accepted anyway because of the large number of countries that did not vote. (default vote of 'yes').
- As a result DGMR is questioning the ISO 9613 recommendations and therefore in the DGMR software the user can select the following settings
  - According to ISO 9613.2 This is the original ISO 9613.2 implementation.
  - With reasonable suggestions
    This is an adapted ISO 9613.2 implementation with those recommendations that were supported by all (active) members of the ISO 17534 working group.
  - With suggestions in discussion
    This is an adapted ISO 9613.2 implementation supporting all recommendations including the ones without consensus within the ISO 17534 working group.



## Summery and conclusions

- What is noise prediction and noise mapping
- Field of application
- Error propagation
- Good practice guide



- Software is not the same as an calculation standard
- Uncertainty caused by unclear methods
- Quality assurance for noise calculation software ISO 17534









# Thanks for your attention

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